

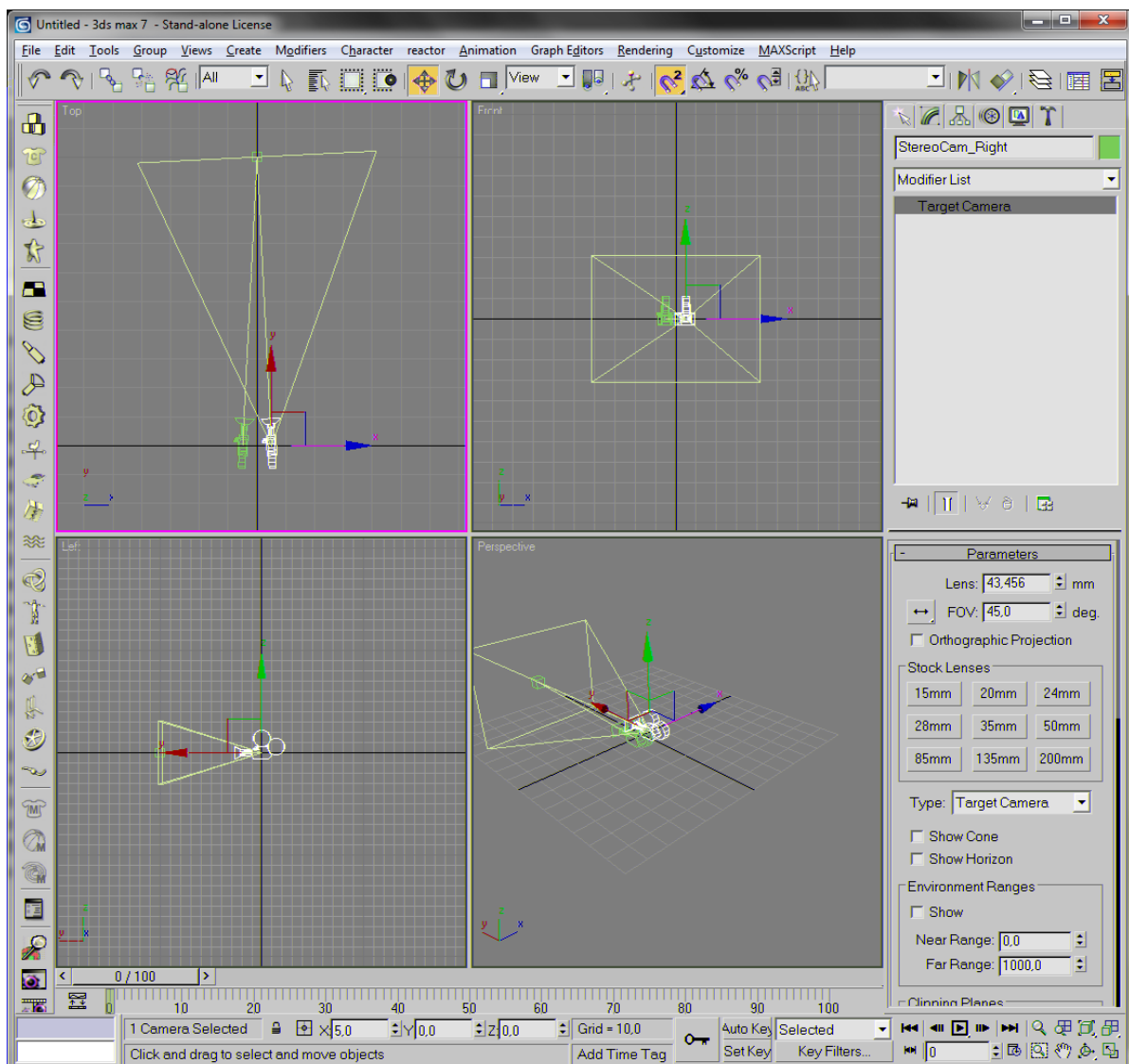
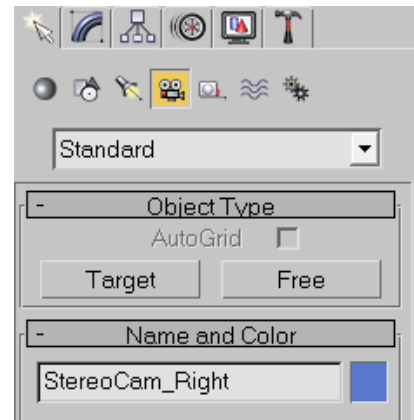


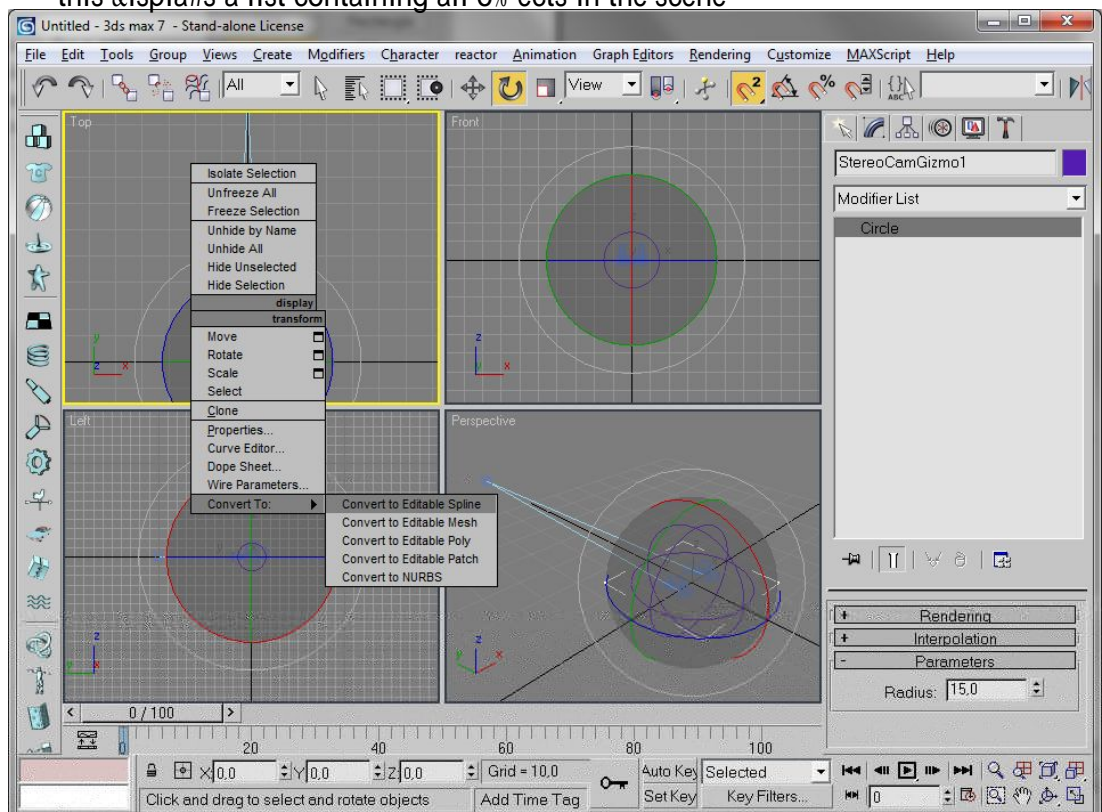
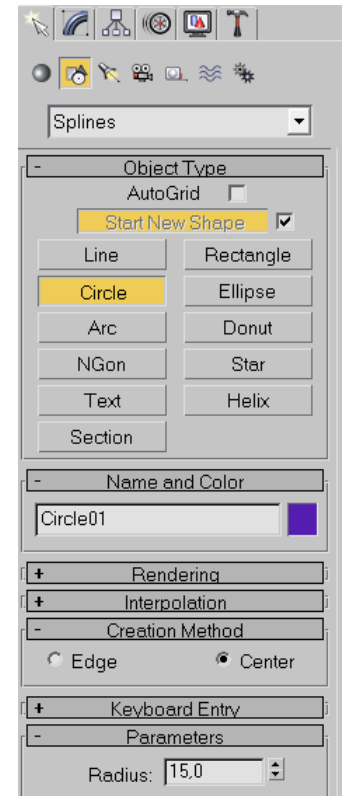
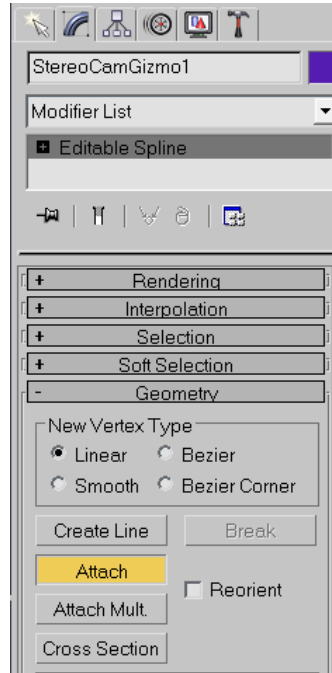
Stereoscopic 3D Visualization




Tutorial: How to create a Stereoscopic 3D Camera in 3ds Max

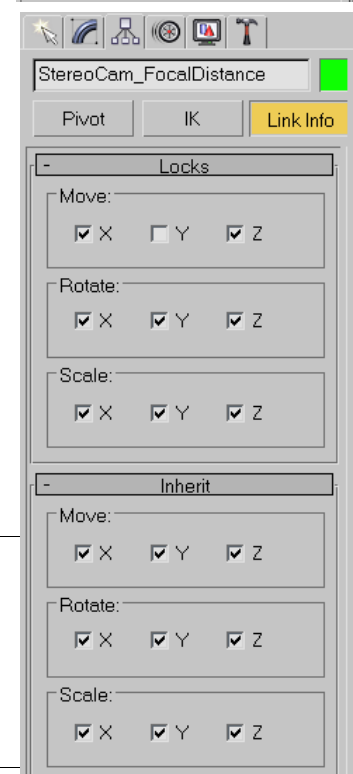
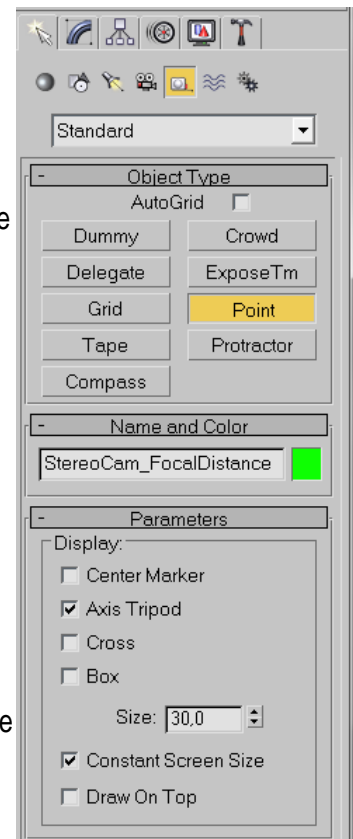
- first create two target cameras 
- set the Snaps Toggle to 2D 
- create the first target camera (Image right)
- place the camera at (0,0,0)
- place the camera target at (100,0,0)
- name it: "StereoCam_ ight!"
- make a copy of this camera (e.g. by pressing shift and dragging StereoCam_ ight to move)
- name it: "StereoCam_ (eft!"
- place the camera at (0,0,0)
- place the camera target at (100,0,0)
- define the eye distance
 - now decide the distance for both eyes, we will take now a distance of 10
 - place the StereoCam_ ight at (0,0,0)
 - place the StereoCam_ (eft at (0,10,0) (Image bottom)



- group the camera
 - now we have to make sure that we can move both cameras as one object. the first idea is to create a simple group containing only the two camera objects, but this will be a problem when the position and rotation will be changed, e.g. if they are attached to a path. Therefore, an alternative is chosen:
 - create a / i0mo
 - create a simple circle with radius 1 (Image right)
 - place it in point (0,0,0), it is still included and now both cameras
 - make two duplicates (again don't can press shift and move separately or 'se CT' (12 for this purpose)
 - rotate the 1st duplicate to 304 along the x axis
 - rotate the 2nd duplicate to 304 along the y axis
 - name them e.g. StereoCam / i0mo1 to 6
 - right click on StereoCam / i0mo1 and select:
 - "Convert to Editable Spline" (Image bottom)
 - select now this Editable Spline and attach the two other circles to it (Image center) by clicking them in the viewport. alternatively don't can also 'select this and display a list containing all objects in the scene

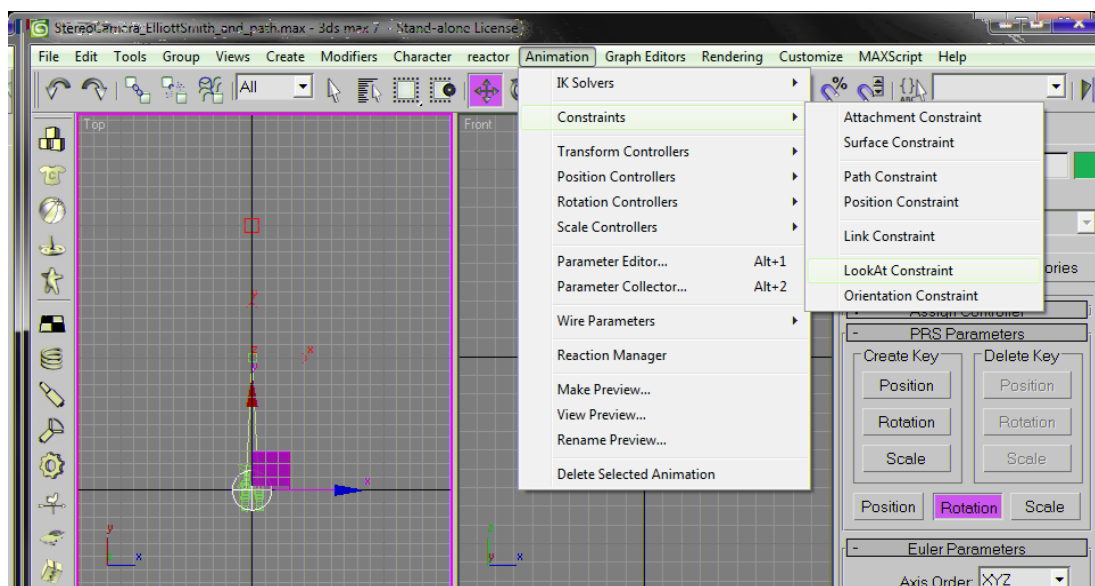
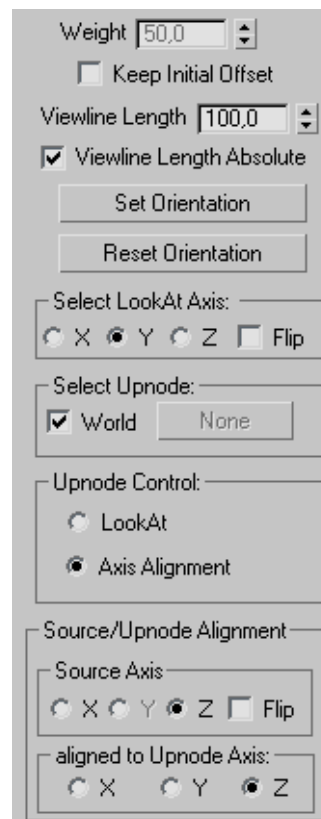
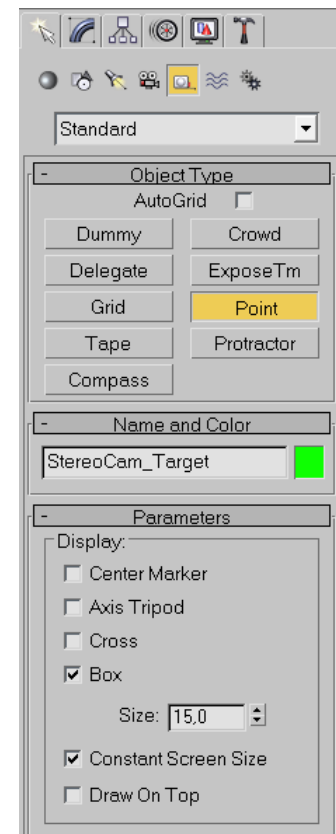


- now this object has to be linked to the cameras: select the StereoCam_ right, press the link button  and select the StereoCam / i0mo1
- go back to the  stand and move it by pressing the  button
- then repeat the procedure for the StereoCam_ (left)
- this step is finished, now both cameras simulate stereo
- rename the object finally to: "StereoCam_ / i0mo1"
- create the Local Distance
 - we still have to separate camera targets, therefore we have to change the names StereoCam_ (left)Target and StereoCam_ rightTarget. We will combine these objects now
 - create the helper object "Distance" and take the options listed shown at the Image right: select "Distance" with a Size of 60 and select "Constant Screen Size"
 - name it: "StereoCam_LocalDistance"
 - place it at (0,100,0)
 - now we have to apply the procedure for the Distance to the focal distance object:
 - select StereoCam_ rightTarget
 - press the link button again
 - select StereoCam_LocalDistance
 - and, vice versa for StereoCam_ (left)Target
 - still, we can move StereoCam_LocalDistance in all directions. If we do not want this, because the movement would not be natural. Instead place it around with the object and it will see therefore we will lock now the movement:
 - select StereoCam_LocalDistance from the hierarchy menu (Image right bottom)
 - select all checkboxes except = rotate, >
 - now we can move the focal distance only along the viewing axis of the cameras
 - the last problem to solve in this issue gets apparent if we select the StereoCam_ / i0mo and move it into all directions: the StereoCam_LocalDistance remains at its point. To solve this issue, we have to link the StereoCam_LocalDistance to the StereoCam_ / i0mo the way we link it before with the other objects
 - now we have to change two target cameras to one stereoscopic camera which is able to change the focus point. On our way to this point, we lost the target, so let's reimplement the target



– this tutorial is based on:
 Creating a Stereoscopic Camera rig in 6s = a5
<http://www.robott.com/watch/AN9nheBCTD=7>
 Created by: **Elliott Smith**, Eigsaw Systems (t&B-Frn Sommer for C7 (microcosmos.org)

- recreate the target
 - create a new 'mm# o%-ect as shown on the Image left, with a size of 1), "Bo5! an& again "Constant Screen Size! select&
 - place it at (0,200,0)
 - name it "StereoCam_Target!
 - now the movement of the camera has to be connected to the movement of the StereoCam_Target:
 - select the StereoCam_ / iomo
 - select from the menu ' ; nimation G Constraints G (oo" ; tConstraint
 - select the StereoCam_Target (Image %ottom)
 - now #o' will see, that the cameras are pointing into the wrong &irection& therefore #o' ha,e to select 'n&er the term "Select (oo" ; t ; 5is! : > in the giomo properties in the categor# " (oo" ; tConstraint! (the giomo properties are also fo'n& at Image %ottom on the right si&e& #o' ha,e to scroll &own to fin& "Select (oo" ; t ; 5is!)
 - it loo"s alrea&# correct, %'t if we wo'l& pla# aro'n& with the camera, we wo'l& fin& o't, that the positions of the cameras are switching if we cross the H a5is, therefore we also ha,e to ma"e s're, that the "So'rce ; 5is! is D, the "align& to I pno& ; 5is! is D an& that the " J orl&! is select& 'n&er "Select I pno&! (Image center)



- Now we have the Key Objects created:
 - StereoCam_ / i0mo
 - StereoCam_9ocalDistance
 - StereoCam_Target
 - StereoCam_ (eft
 - StereoCam_ (eft\$Target
 - StereoCam_ ight
 - StereoCam_ ight\$Target
 - the last 6 objects are obsolete for the further work, therefore I would suggest to freeze them, - 'st to prevent that they are selected - 'st select this 6 objects, right click on one of them and select: Freeze selection the objects are now gray and can not be selected anymore, - 't if the remaining 6 objects are transformed, they behave as suggested to
- a camera path for testing
 - the stereo camera is complete, so - 'st let 's create a small test environment
 - create a teapot (a Standard Primitive of 6.5 = 6.5) with a size of 100, place it in the center at (0,0,100)
 - place the StereoCam_ / i0mo at (0,100,0)
 - create a line which starts in (0,100,0) and ends at (0,200,0)
 - attach - 'st the line as shown in Image 10: select the line in position mode, select the starting vertex and attach - 'st the teapot's center by dragging the tangent (top view of Image 10)
 - select the StereoCam_ / i0mo and go to the menu: Animation > Constraints > Path constraint

